WEST Search History

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DATE: Thursday, December 18, 2008

Hide?	Set Name	Query	Hit Count
		DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ	
☐	L49	camera and L48	18
☐	L48	article handling same robot$6 and identify$3	55
		DB=USPT; PLUR=YES; OP=ADJ	
☐	L47	(("7313464" | "7123992" | "6886231" | "6597971" | "6463360")!.PN.). USPT.	5
		DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ	
☐	L46	L44 and L45	170
☐	L45	ccd or camera or video and L44	909151
☐	L44	L42 and L43	291
☐	L43	condition or if and L42	4489197
☐	L42	L40 and L41 and pick up	499
☐	L41	(robot$6 or articulat$3 or automat$6 or autonomous$2 or CNC or machine$2 or mechanical device or mechan$6 or servomechan$4)	8623526
☐	L40	(700/245 or 247,248,250,251,252,253,254,255,257,259,260,262,264 or 318/568.1 |318/568.11 |318/568.14 |318/568.16 |318/568.21 |318/568.23 or 901/4 |901/43 |901/47).ccls.	5466
☐	L39	marc.xa. and robot and pick up	90
☐	L38	L34 and L37	63
☐	L37	detect$5 and L36	151
☐	L36	result and L35	170
☐	L35	L33 and section$2 same regions	177
☐	L34	(visual sensor or camera) and L33	640
☐	L33	(pickup or "pick and place") same robot$6	1870
☐	L32	10/701596	2

☐	L31	article pickup and robot$	90
☐	L30	(6328523 | 6141863).pn.	4

DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ

☐	L29	L27 and detect$3	206
☐	L28	L27 and deterct$3	0
☐	L27	L25 and L26	242
☐	L26	identify$3 and L25	242
☐	L25	database and L24	267
☐	L24	computer and L23	719
☐	L23	sens$4 and L22	1228
☐	L22	table and L21	3155
☐	L21	wheelchair or wheel chair and L20	29682
☐	L20	marc.xa. and robot	712

DB=PGPB; PLUR=YES; OP=ADJ

☐	L19	marc.xa. and robot	0
☐	L18	marc.xa. and wheelchair and robot	0
☐	L17	marc.xa. and wheel chair and robot	0
☐	L16	history and L15	9
☐	L15	article and L14	15
☐	L14	table and map and L13	39
☐	L13	robot$6 and L12	118
☐	L12	sens$3 and L11	743
☐	L11	reference image and camera image	1013
☐	L10	reference image and camera image and dirrerential image	0
☐	L9	10/532157	1

DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ

☐	L8	article and handling and L6	37
☐	L7	article handling and L6	1
☐	L6	handling right and determining and database	47
☐	L5	handling same right adj6 determining and database	3

☐	L4	robot$6 and l3	1
☐	L3	handling same right adj6 determining	7
☐	L2	handling same right same determing	0
☐	L1	handling same right adj5 determing	0

END OF SEARCH HISTORY